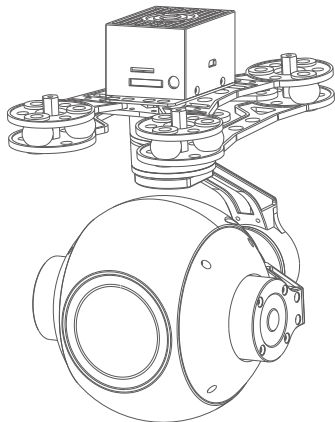




## User manual

### Q30T

30x Optical Zoom Object Tracking Camera Gimbal



Images are for reference only, please subject to the actual product.

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## Gimbal Introduction

Q30T is a pinpoint-precision professional 3-axis gimbal which features high stability, small size, light weight and low power consumption. The 3-axis gimbal based on FOC motor control technology, adopts pinpoint-precision encoder in each motor.

The speed of Q30T gimbal is adjustable, LOW speed mode is used for large zoom range, the control will be more accurate; Fast speed mode is used for small zooming range, which makes the gimbal control sensitive and quick. Also the one-key to center function will allow the gimbal return to initial position automatically and rapidly.

Q30T supports PWM, S.BUS and serial command control, suitable for close range remote control or remote data command control.

## Object Tracking Function

### 1.Function description

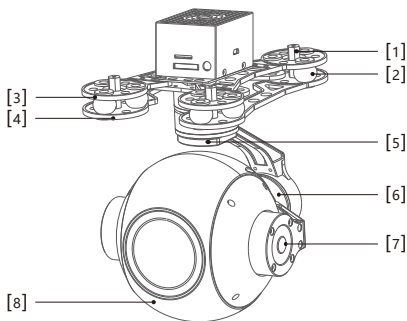
Build-in normalization, cross-correlation and tracking algorithm, combining with object missing recapture algorithm, achieve stable track of the target.

Support custom characters of user OSD, adaptive gate, cross cursor, tracking information display.

### 2.Tracking performance

- 1)Update rate of deviation pixel 50Hz
- 2)Output delay of deviation pixel <10ms
- 3)Minimum object contrast 5%
- 4)The minimal signal-to-noise ratio (SNR) 4
- 5)Minimum object size 16\*16 pixel
- 6)Maximum object size 160\*160 pixel
- 7)Tracking speed 32 pixel/frame
- 8)The mean square root values of pulse noise in the object position<0.5 pixel
- 9)Object memory time 100 frames

## Gimbal Description



[1] Gimbal fixed copper cylinder

[2] Damping ball

[3] Upper damping board

[4] Lower damping board

[5] YAW axis motor

[6] Roll axis motor

[7] Pitch axis motor

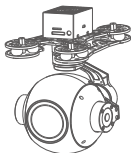
[8] HD zoom camera



Please make sure that the motor is not stopped by any object during the rotation, if the gimbal is blocked during rotation, please remove the obstruction immediately.

## Packing list

Gimbal\*1



Screw pack\*1

M3\*5mm button head hexagon screw\*12  
( fixed copper cylinder and damping plate)

Copper cylinders\*4

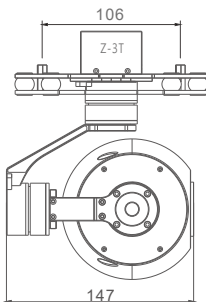
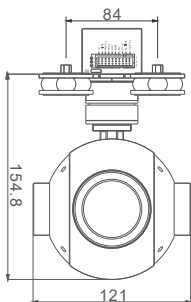


Damping balls\*12

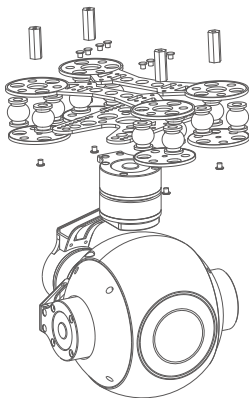


## Gimbal Dimension

Unit : mm



## Installing



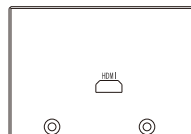
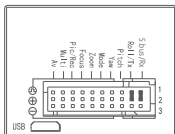
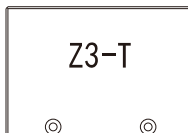
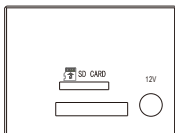
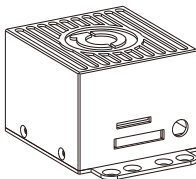
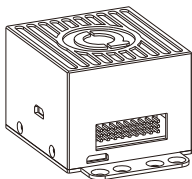
### Mechanics@Electronic Characteristics

Input voltage	3S~4S	Idle current	330mA@12V
Dynamic current	450mA@12V	Working environment temp	-20℃ ~ +80℃
Size	L147 *W 121*H154.8mm	Weight	720g

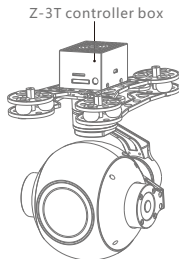
### Working Characteristics

Pitch/Tilt: Pitch angle range of action : $\pm 90^\circ$
Roll: Roll angle range of action : $\pm 85^\circ$
Yaw/Pan: Yaw angle range of action : $\pm 150^\circ$
Vibration angle: Pitch/Roll: $\pm 0.02^\circ$ , Yaw: $\pm 0.03^\circ$

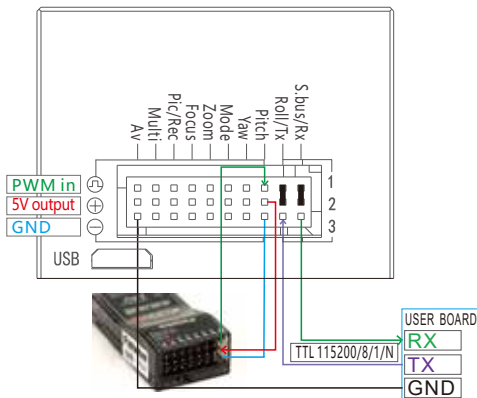
## Gimbal's Signal Wire Box



## Connection of Control Box and Wiring Instruction



HDMI: micro HDMI OUTPUT  
1080P 60fps default  
SD card: max 32G, class10  
FAT 32 or exFAT format

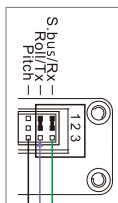
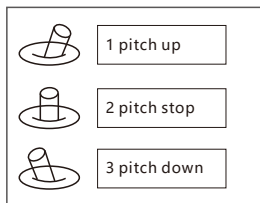




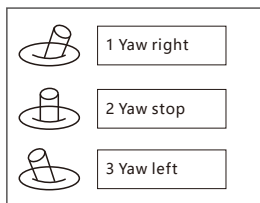
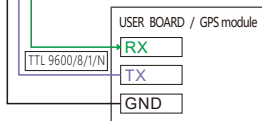
S.bus/Rx: connect to Rx2 for track function.

Roll/ Tx: connect to Tx2 for track function.

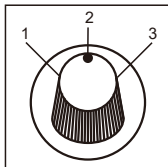
Pitch: PWM in, pitch control



We have protocol for control the gimbal and camera, please contact our technical support for detail doc.



Mode: Change the speed / home position



Position 1: Lowest speed for pitch and yaw.

Position 2: Middle speed for pitch and yaw.

Position 3: Highest speed for pitch and yaw. The speed is continuously quickly from 1 to 3.

One click: Home position.

Two click: Look down.

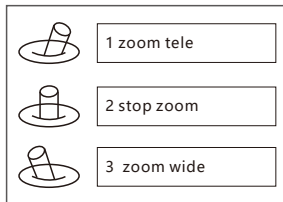
Three click: Yaw not followed by frame.

Four click: Yaw followed by frame.

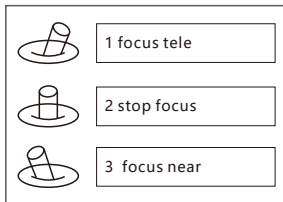
Five click: Restore the factory settings.

(Click = from 2 to 3 and back to 2 quickly)

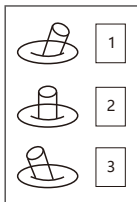
**ZOOM:** Zoom the camera



**Focus:** Focus the camera

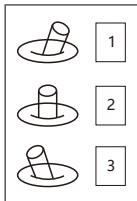


## Pic/ Rec picture / Start record, stop record



- 1 Switch 2 to 1: Start record / stop record. Start record, the OSD display rec hh:mm:ss ;
- 2 Stop record, the OSD display STBY.
- 3 Switch 2 to 3: Take a picture. OSD display 'REC IMG' a second.

## Multi: Tracking control



- 1: Position 1 exit the tracking  
Switch 1 to 2: display the cross cursor. Adjust the object to the cross cursor.
- 2: Switch 2 to 3: start tracking. Change the object during tracking.

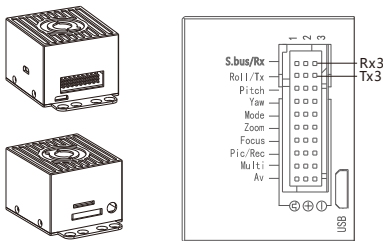
AV: NO AV output this model.

## 30x Starlight Camera Introduction

		FCB-EV7520
Imager sensor		1/2.8-type Exmor R CMOS
Lens		30x
Picture quality		Full HD 1080p (1920 x 1080)
Minimum illumination*		Colour: 0.01 lx (F1.6, AGC on, 1/30 s)
Digital zoom		12x (360x with optical zoom)
Defog		●
Image sensor		1/2.8-type Exmor R CMOS
Image sensor (Number of effective pixels)		Approx. 2.13 Megapixels
Signal system		1080p/59.94, 1080p/50, 1080p/60, 1080p/30, 1080p/29.97, 1080p/25, 1080i/59.94, 1080i/50, 1080i/60, 1080i/30, 720p/59.94, 720p/50, 720p/60, 720p/30, 720p/29.97, 720p/25, NTSC*1, PAL*1
Minimum illumination (50%)	High sensitivity mode	Colour: 0.01 lx (F1.6, AGC on, 1/30s)
	Normal mode	Colour: 0.1 lx (F1.6, AGC on, 1/30s)
S/N ratio		More than 50 dB
Gain		Auto/Manual 0 dB to 50.0 dB (0 to 28 steps +2 step/ total 15 steps)
		Max. Gain Limit 10.7 dB to 50.0 dB (6 to 28 steps +2 step/ total 12 steps)

		<b>FCB-EV7520</b>
Shutter speed		1/1 s to 1/10,000 s, 22 steps
Sync system		Internal
Exposure control		Auto, Manual, Priority mode (shutter priority & iris priority), Bright, EV compensation, Slow AE
Backlight compensation		Yes
Aperture control		16 steps
White balance		Auto, ATW, Indoor, Outdoor, Outdoor Auto, Sodium Vapor Lamp (Fix/Auto/Outdoor Auto), One-push, Manual
Lens		30x optical zoom f = 4.3 mm (wide) to 129.0 mm (tele) F1.6 to F4.7
Digital zoom		12x (360x with optical zoom)
Focusing system		Auto (Sensitivity: normal, low), One-push AF, Manual, Interval AF, Zoom Trigger AF, Focus compensation in ICR on
Horizontal viewing angle	1080p mode	63.7° (wide end) to 2.3° (tele end)
	720p mode	63.7° (wide end) to 2.3° (tele end)
	SD	47.8° (wide end) to 1.7° (tele end)
Minimum object distance		10 mm (wide end) to 1200 mm (tele end) (Default: 300 mm)

## GPS Information Display and Serial Port Control Wiring Diagram



To use the serial port function, please use the jumper cap to connect RX1 and RX2, TX1 and TX2.

External serial port TX connect with TX3. External serial port RX connect with RX3. External serial port GND connect with GND of wiring box.

**Note: The signals in the black square are all TTL serial ports. Do not connect 5V and GND to serial data Interface!**

The output of data radio stations (TTL 3.3 V) directly controls the gimbal and camera movements, in which the gimbal actions include:

- 1, Yaw control and angle output, pitch control and angle output, speed setting, angle setting, stop, return to Home;
- 2, camera actions include: zooming, focusing, start record, stop record, taking photos, record / photo Switch, zoom times information output, etc;
- 3, when there is no respond on the command from the control box, you need to enter the enquiry command to obtain the status of camera gimbal;
- 4, serial port baud rate 115200, 8-bit data bit, 1 stop bit, no check bit, HEX.

**For specific protocols, please contact us for technical support.**